

Lateral Torsional Buckling of Wooden Beams with Mid-span Lateral Bracing offset from Section Mid-height

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Abstract:

An energy-based solution is developed for the lateral torsional buckling analysis of wooden beams with a mid-span lateral brace subjected to uniformly distributed loads or mid-span point load. The predicted critical moments and mode shapes are shown to agree with results based on three-dimensional finite element analysis. The study indicates that such beams are prone to two buckling patterns: a symmetric mode and an anti-symmetric mode. Whether the symmetric or the anti-symmetric mode governs the critical moment capacity is shown to depend on the bracing height. A technique is then developed to determine the threshold bracing height required to maximize the critical moment. A parametric study is then conducted to investigate the effect of lateral bracing and load height effects on the critical moments. Simple design equations are developed to predict critical moments for a practical range of cases. The limitations of the simplified procedure are discussed. For cases outside the scope of the simplified procedure, designers are recommended to adopt the more detailed energy-based solution. Design examples are provided to illustrate the merits and applicability of the proposed procedure in practical situations.

Keywords

Lateral torsional buckling, lateral bracing, load height, bracing height, simplified design equations

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38 **Introduction and Literature review**

39 Design standards (e.g., CAN-CSA-O86 2014, NDS 205) recognize lateral torsional buckling (LTB)
40 as a failure mode potentially governing the capacity of long span laterally unsupported wood
41 beams. The phenomenon has been experimentally documented (e.g., Hooley and Madsen, 1964
42 and Xiao, 2014). The LTB resistance of such beams is known to be influenced by the load height
43 effect and by the presence of lateral bracing provided by adjoining members. In practical design,
44 such beams may be laterally restrained at mid-span with braces offset from the section mid-height.
45 Lateral restraints would typically be placed at the top face by means of secondary beam elements,
46 blocking and/or bracing of closely spaced joist elements, or through diaphragm action. In such
47 details, the lateral restraint at top of the beam braces the compression face (when subjected to
48 downwards vertical loading) is consistent with the understanding that it optimizes the LTB
49 capacity of the member. There are cases however that deviate from this convention, including the
50 design of beams for wind uplift, where lateral braces located at beam top would provide bracing
51 near the tension side of the member (Du et al. 2016a, 2016b). A similar situation arises for beam-
52 columns on the leeward side of a building. Additionally, situations arise where the load height and
53 the bracing height may coincide. When such details are encountered, it becomes difficult for the
54 designer to assess the beneficial contribution of the brace on the lateral torsional buckling capacity.
55 Currently, there are no provisions in design standards (CAN-CSA O86 2014, NDS 2015) that
56 address such cases, and the present study provides a model and a simple expression to aid the
57 designer in evaluating whether a lateral brace offset from the compression face or the neutral axis
58 can be considered to optimize the resistance for LTB failure.

59 Wood design recommendations (e.g., AFPA 2003) and structural steel standards (e.g., CAN-CSA
60 S16 2014, AS4100 1998, Eurocode 2005, AISC 2010) account for the effect of load height and

61 presence of lateral bracing systems, either through the effective length approach, the equivalent
62 moment factor approach, or other approximate methods. However, no recommendations are
63 provided to account for the influence of bracing heights. Within this context, the present study
64 investigates the combined effect of load height and bracing height on the lateral torsional buckling
65 capacity of simply supported wood beams.

66 **Load height effect**

67 The load height effect on lateral torsional buckling has been heavily investigated for steel beams
68 and, to a limited extent, for wood beams. The present review covers both types of applications
69 given their mechanistic commonalities. It is cautioned however that while gravity loading at the
70 bottom flange is possible in steel beams, such loading is discouraged in wood beams given that it
71 is associated tensile stresses perpendicular to the grain, which could lead to premature failure.
72 Early work includes the work Prescott and Carrington (1920), Timoshenko (1936), Winter (1941),
73 Schrader (1941), Austin et al. (1955), Pettersson et al. (1952). Kerensky et al. (1956) developed a
74 solution that captures the effect of top flange loading for beams by introducing the effective length
75 approach. Nethercot and Rockey (1971) accounted for the load height effect for simply supported
76 beams by introducing design coefficients in critical moment equations. Based on the Rayleigh-
77 Ritz method, JingPing et al. (1988) evaluated the inelastic LTB capacity of beam-columns
78 subjected to two symmetric transverse loads. Helwig et al. (1997) and Samanta and Kumar (2006)
79 investigated the load height effect by conducting a shell-based finite element analysis (FEA) for
80 mono-symmetric beams. A few studies investigated cases involving top flange, mid-height and
81 bottom flange loading: Yura et al. (2008) developed an expression for the elastic critical moment
82 for twin girders with doubly symmetric and singly symmetric cross sections. White and Kim (2008)
83 conducted experiments to verify LTB predictions in AASHTO (2004) and AISC (2005).

84 Mohebkhah (2010) developed an FEA model to investigate inelastic LTB capacity of simply
85 supported I-beams. Wong et al. (2015) compared previous design recommendations with
86 experimental results of White and Kim (2008) and extended the effective length factor concept to
87 a variety of loading scenarios for simply supported beams. While the above studies were primarily
88 aimed at examining the load height effect on LTB resistance, the topic has been partly investigated
89 in various investigations such as Ings and Trahair (1987), Pi et al. (1992), Andrade and Camotim
90 (2005), Mohri and Potier-Ferry (2006), Andrade et al. (2007), Erkmen and Mohareb (2008), Wu
91 and Mohareb (2010), Trahair (2013), Lamb and Eamon (2015), Sahraei et al. (2015), and Sahraei
92 and Mohareb (2016). A common observation in the above studies is that the elastic and inelastic
93 LTB resistances for beams decrease as the point of application of loads induced by gravity moves
94 upwards.

95 **Lateral restraint effect**

96 The effect of continuous rigid lateral top-flange bracing on the LTB analysis of simply supported
97 beams was investigated by Park et al. (2004) by developing a FEA model. A comparison of the
98 results has shown that the moment gradient factor equation of Yura (1993) leads to un-conservative
99 results for uniformly distributed loads. For such cases, Park et al. (2004) proposed supplementary
100 design equations. Samanta and Kumar (2008) developed a FEA model for the LTB analysis of
101 mono-symmetric cantilever I-beams with three types of rigid lateral braces at top flange, bottom
102 flange, and both flanges. For long span beams, top flange bracing was found to be more effective
103 than bottom flange bracing and corresponded to a significant increase in buckling capacity.
104 Bracing both flanges was reported to be most effective in increasing the LTB capacity. For short
105 span beams, lateral bracing at top and bottom flanges was found to be only moderately effective.

106 Several experimental and analytical studies have investigated the effect of flexible lateral restraint
107 on the LTB capacity (e.g. Flint, 1951). In the above studies, top flange lateral bracing was observed
108 to significantly increase the LTB resistance of beams when compared to shear centre or bottom
109 flange bracing.

110 Only a few studies investigated the combined effect of load height and lateral bracing height.
111 Schmidt (1965) analytically and numerically investigated the LTB of beams with central lateral
112 bracing subjected to mid-span point loading. The lateral bracing point coincided with the loading
113 point and both were assumed to be offset from the shear centre. Kitipomchai et al. (1984)
114 investigated the LTB of cantilever I-beams with offset intermediate restraint and vertical loads.
115 Wang et al. (1987) numerically determined the LTB capacity of mono-symmetric cantilevers with
116 eccentric vertical loading and discrete lateral bracing offset from the shear centre. Both studies
117 (Kitipomchai, 1984 and Wang et al., 1987) did not specifically address the benefits of bracing
118 height. McCann et al. (2013) investigated simply supported beams with doubly symmetric I
119 sections subjected to uniform moments with discrete equally spaced eccentric linearly elastic
120 braces. In the study, the lateral bracing point was assumed to coincide with the loading point and
121 the warping effect was omitted. The study did not investigate the load height effect. Within this
122 context, the present study investigates the combined effect of bracing height and load height on
123 the elastic LTB capacity of wooden beams with emphasis on: (a) developing a mathematical model
124 able capture the important characteristics of the solution, (b) investigating the effect of bracing
125 height on the LTB capacity and mode shapes, (c) conducting a parametric study to investigate the
126 effects of key parameters on the LTB resistance, and (d) developing simplified equations for
127 bracing height requirement and corresponding critical moments.

128 **Statement of the Problem**

129 A wooden beam with a doubly symmetric cross-section is simply supported relative to the vertical
130 and lateral displacements and twist at both ends. The beam is subjected to a reference distributed
131 load $q(z)$ offset from the section mid-height axis by a height a taken as positive when the load
132 is above the section mid-height. A mid-span lateral brace offset from the section mid-height is
133 provided at a height b taken as positive when above the section mid-height (Fig. 1). The reference
134 loads $q(z)$ are assumed to increase to reach a critical value $\lambda q(z)$ where the system becomes in
135 a neutral state of stability, at which it has a tendency to undergo lateral torsional buckling without
136 further increase in loading. It is required to determine the critical load magnitude $\lambda q(z)$ at the
137 onset of buckling.

138 **Assumptions**

139 The following assumptions are made

- 140 1. The material is linearly elastic and orthotropic. Given that properties of wood in the
141 tangential and radial directions are nearly equal (FPL, 2010), the nine orthotropic constitutive
142 constants are shown to reduce to six (Xiao 2014). A sensitivity study based on a 3D finite element
143 buckling analysis (Xiao et al. 2014) has shown that the elastic lateral buckling resistance of beams
144 is influenced only by two constitutive properties: the longitudinal Young's modulus E and the
145 shear modulus G for shear stresses acting on the normal plane. The study has shown that changing
146 the remaining material properties by +/-50% influence the predicted critical moments by less than
147 1%. Thus, the present study characterizes the constitutive behaviour of wood using only constants
148 E and G in a manner similar to isotropic materials.
- 149 2. Load distribution is symmetric about the beam mid-span.

150 3. The direction of applied load is constant (i.e., conservative loading), and

151 4. Cross-sectional distortions and shear deformations are negligible

152 **Formulation**

153 **Variational Principle**

154 The total potential energy $\pi = U + V$ is the summation of the internal strain energy U and the
155 load potential energy gained V . The internal strain energy U is given by (e.g., Trahair 1993)

$$156 \quad U = \frac{1}{2} \int_0^L EI_{yy} u''^2 dz + \frac{1}{2} \int_0^L GJ \theta'^2 dz + \frac{1}{2} \int_0^L EC_w \theta''^2 dz \quad (1)$$

157 where $u = u(z)$ is lateral displacement, $\theta = \theta(z)$ is the twist angle, both being functions of the
158 longitudinal coordinate z , L is the span, E is Young's modulus, I_{yy} is the weak moment of
159 inertia, G is shear modulus, J is the Saint-Venant torsional constant, and C_w is the warping
160 constant. The load potential energy gained by the load V consists of two components $V = V_1 + V_2$
161 and is given by (e. g., Trahair 1993)

$$162 \quad V_1 = \lambda \int_0^L M(z) \theta u'' dz, \quad V_2 = -\frac{\lambda}{2} \int_0^L q(z) a \theta^2 dz \quad (2)a,b$$

163 where V_1 is the load potential energy gained by the strong axis bending moments $M = M(z)$
164 induced by the transverse loads, undergoing lateral displacements $u(z)$ and angle of twist $\theta(z)$
165 and V_2 is the load potential gained by the distributed load $q(z)$ acting at a distance a above the
166 section mid-height undergoing an angle of twist $\theta(z)$ and λ is a load multiplier to determined
167 based on a buckling analysis.

168 **Assumed Displacement Functions**

169 The displacement functions are assumed to take the form

170
$$u(z) = \left(\sum_{i=1}^{2n} A_i \sin \frac{i\pi z}{L} \right) + A_{2n+1} \sin \frac{(2n+1)\pi z}{L}, \quad \theta(z) = \sum_{j=1}^{2n} B_j \sin \frac{j\pi z}{L} \quad (3),(4)$$

171 The above displacement functions meet the essential and natural boundary conditions
 172 $u(0) = u''(0) = u(L) = u''(L) = 0$ and $\theta(0) = \theta''(0) = \theta(L) = \theta''(L) = 0$. The presence of a mid-
 173 span lateral brace at a height b above section mid-height provides a kinematic constraint between
 174 the displacement $u(L/2)$ and the angle of twist $\theta(L/2)$ at beam mid-span. From Fig. 2, one
 175 obtains the kinematic constraint $u(L/2) = -\theta(L/2)b$. From Eqs. (3) and (4) by setting $z = L/2$,
 176 and substituting into the kinematic constraint equation, one can express constant A_{2n+1} in terms of
 177 the remaining constants A_i, B_i ($i = 1, \dots, n$) as $A_{2n+1} = -\sum_{i=1}^{2n} (-1)^n (A_i + bB_i) \sin(i\pi/2)$. Then, from
 178 the expression for A_{2n+1} , by substituting into Eq.(3), one obtains

179
$$u(z) = \sum_{i=1}^{2n} A_i \left[\sin \frac{i\pi z}{L} + (-1)^{n+1} \sin \frac{i\pi}{2} \sin \frac{(2n+1)\pi z}{L} \right] + b \sum_{i=1}^{2n} B_i (-1)^{n+1} \sin \frac{i\pi}{2} \sin \frac{(2n+1)\pi z}{L} \quad (5)$$

180 **Internal Strain Energy**

181 From Eqs. (4) and (5), by substituting into the internal strain energy expression given in Eq.(1),
 182 one obtains

183
$$U = \frac{1}{2} \langle \mathbf{A}_a^T \quad \mathbf{A}_b^T \rangle \begin{bmatrix} \mathbf{k}_1 & \mathbf{0} \\ \mathbf{0} & \mathbf{k}_2 \end{bmatrix} \begin{Bmatrix} \mathbf{A}_a \\ \mathbf{A}_b \end{Bmatrix} \quad (6)$$

184 where

$$\begin{aligned}
\mathbf{A}_a^T{}_{1 \times 2n} &= \langle A_2 \quad B_2 \quad A_4 \quad B_4 \quad \cdots \quad A_{2n} \quad B_{2n} \rangle, \mathbf{A}_b^T{}_{1 \times 2n} = \langle A_1 \quad B_1 \quad A_3 \quad B_3 \quad \cdots \quad A_{2n-1} \quad B_{2n-1} \rangle, \\
\mathbf{k}_1 &= \begin{bmatrix} \mathbf{m}_{1,1} & \mathbf{m}_{1,3} & \cdots & \mathbf{m}_{1,2i-1} & \cdots & \mathbf{m}_{1,2n-1} \\ \mathbf{m}_{3,1} & \mathbf{m}_{3,3} & \cdots & \mathbf{m}_{3,2i-1} & \cdots & \mathbf{m}_{3,2n-1} \\ \vdots & \vdots & \ddots & \vdots & \ddots & \vdots \\ \mathbf{m}_{2j-1,1} & \mathbf{m}_{2j-1,3} & \cdots & \mathbf{m}_{2j-1,2i-1} & \cdots & \mathbf{m}_{2j-1,2n-1} \\ \vdots & \vdots & \ddots & \vdots & \ddots & \vdots \\ \mathbf{m}_{2n-1,1} & \mathbf{m}_{2n-1,3} & \cdots & \mathbf{m}_{2n-1,2i-1} & \cdots & \mathbf{m}_{2n-1,2n-1} \end{bmatrix}, \mathbf{k}_2 = \begin{bmatrix} \mathbf{m}_{2,2} & \mathbf{m}_{2,4} & \cdots & \mathbf{m}_{2,2i} & \cdots & \mathbf{m}_{2,2n} \\ \mathbf{m}_{4,2} & \mathbf{m}_{4,4} & \cdots & \mathbf{m}_{4,2i} & \cdots & \mathbf{m}_{4,2n} \\ \vdots & \vdots & \ddots & \vdots & \ddots & \vdots \\ \mathbf{m}_{2j,2} & \mathbf{m}_{2j,4} & \cdots & \mathbf{m}_{2j,2i} & \cdots & \mathbf{m}_{2j,2n} \\ \vdots & \vdots & \ddots & \vdots & \ddots & \vdots \\ \mathbf{m}_{2n,2} & \mathbf{m}_{2n,4} & \cdots & \mathbf{m}_{2n,2i} & \cdots & \mathbf{m}_{2n,2n} \end{bmatrix}
\end{aligned}
\tag{185}$$

$$\mathbf{m}_{j,i} = \begin{bmatrix} m_{1,i,j} & 0 \\ 0 & m_{3,i,j} \end{bmatrix} + b \begin{bmatrix} 0 & m_{2,i,j} \\ m_{2,i,j} & 0 \end{bmatrix} + b^2 \begin{bmatrix} 0 & 0 \\ 0 & m_{4,i,j} \end{bmatrix}
\tag{186}$$

$$\begin{aligned}
m_{1,i,j} &= EI_{yy} \left[\left(\frac{i\pi}{L} \right)^2 \left(\frac{j\pi}{L} \right)^2 \int_0^L \sin \frac{i\pi z}{L} \sin \frac{j\pi z}{L} dz + \frac{L}{2} \sin \frac{i\pi}{2} \sin \frac{j\pi}{2} \left(\frac{(2n+1)\pi}{L} \right)^4 \right] \\
m_{2,i,j} &= \frac{L}{2} EI_{yy} \sin \frac{i\pi}{2} \sin \frac{j\pi}{2} \left(\frac{(2n+1)\pi}{L} \right)^4 \\
m_{3,i,j} &= GJ \left(\frac{i\pi}{L} \right) \left(\frac{j\pi}{L} \right) \int_0^L \cos \frac{i\pi z}{L} \cos \frac{j\pi z}{L} dz + EC_w \left(\frac{i\pi}{L} \right)^2 \left(\frac{j\pi}{L} \right)^2 \int_0^L \sin \frac{i\pi z}{L} \sin \frac{j\pi z}{L} dz \\
m_{4,i,j} &= \frac{L}{2} EI_{yy} \sin \frac{i\pi}{2} \sin \frac{j\pi}{2} \left(\frac{(2n+1)\pi}{L} \right)^4
\end{aligned}
\tag{187}$$

188 Fourier Expansion of bending moments:

189 A given bending moment $M(z)$ can be expressed in a Fourier series as

$$M(z) = \sum_{k=1,2}^{kmax} m_k \sin \frac{k\pi z}{L} \quad m_k = \frac{2}{L} \int_0^L M(z) \sin \frac{k\pi z}{L} dz
\tag{190}$$

191 For the case of a mid-span load, the moment distribution is given by

192 $\lambda M(z) = \lambda Qz/2$, $0 \leq z \leq L/2$ and $\lambda M(z) = \lambda Q(L-z)/2$, $0 \leq z \leq L/2$. By substituting into Eq.

193 (9)b, one obtains $m_k = 2QL/k^2\pi^2$, ($k = 1, 3, 5, \dots$). For the case of a uniformly distributed load λq ,

194 the bending moment expression takes the form $\lambda M(z) = \lambda q(Lz - z^2)/2$. Using the Fourier

195 expansion in Eq.(9), one obtains the Fourier coefficients $m_k = 4\lambda qL^2/(k\pi)^3$ ($k = 1, 3, 5, \dots$)

196 **Destabilizing term due to bending moments**

197 For symmetric loading, it can be demonstrated (Appendix A) that the destabilizing term due to
 198 bending moments takes the form

199
$$V_1 = \frac{\lambda}{2} \langle \mathbf{A}_a^T \quad \mathbf{A}_b^T \rangle \begin{bmatrix} \mathbf{k}_{g1} & \mathbf{0} \\ \mathbf{0} & \mathbf{k}_{g2} \end{bmatrix} \begin{Bmatrix} \mathbf{A}_a \\ \mathbf{A}_b \end{Bmatrix} \quad (10)$$

200 while that the due to load height effect takes the form

201
$$V_2 = \frac{\lambda}{2} \langle \mathbf{A}_a^T \quad \mathbf{A}_b^T \rangle \begin{bmatrix} \mathbf{k}_{g3} & \mathbf{0} \\ \mathbf{0} & \mathbf{k}_{g4(i)} \end{bmatrix} \begin{Bmatrix} \mathbf{A}_a \\ \mathbf{A}_b \end{Bmatrix} \quad (11)$$

202 where the entries of the geometric sub-matrices \mathbf{k}_{g1} , \mathbf{k}_{g2} , $\mathbf{k}_{g3(i)}$, $\mathbf{k}_{g4(i)}$ are provided in Appendix A
 203 for the cases of mid-span point load $i = 1$ and for the case of uniformly distributed load $i = 2$.

204 **Stationarity conditions**

205 From Eqs. (6), (10), and (11), by substituting into $\pi = U + V_1 + V_2$, and evoking the stationarity
 206 conditions $\partial\pi/\partial\mathbf{A}_a = \partial\pi/\partial\mathbf{A}_b = \mathbf{0}$, one obtains

207
$$\left\{ \begin{bmatrix} \mathbf{k}_1 & \mathbf{0} \\ \mathbf{0} & \mathbf{k}_2 \end{bmatrix} + \lambda \left(\begin{bmatrix} \mathbf{k}_{g1} & \mathbf{0} \\ \mathbf{0} & \mathbf{k}_{g2} \end{bmatrix} + \begin{bmatrix} \mathbf{k}_{g3} & \mathbf{0} \\ \mathbf{0} & \mathbf{k}_{g4} \end{bmatrix} \right) \right\} \begin{Bmatrix} \mathbf{A}_a \\ \mathbf{A}_b \end{Bmatrix} = \mathbf{0} \quad (12)$$

208 The two partitions of Eq. (12) can be expanded to yield

209
$$\left(\mathbf{k}_1 + \lambda (\mathbf{k}_{g1} + \mathbf{k}_{g3}) \right) \mathbf{A}_a = \mathbf{0} \quad (13)$$

210
$$\left(\mathbf{k}_2 + \lambda (\mathbf{k}_{g2} + \mathbf{k}_{g4}) \right) \mathbf{A}_b = \mathbf{0} \quad (14)$$

211 The non-trivial solution of Eq. (12) is given by setting the determinant of the matrix of coefficients
 212 to zero, i.e.,

$$213 \quad \begin{vmatrix} \mathbf{k}_1 + \lambda(\mathbf{k}_{g1} + \mathbf{k}_{g3}) & \mathbf{0} \\ \mathbf{0} & \mathbf{k}_2 + \lambda(\mathbf{k}_{g2} + \mathbf{k}_{g4}) \end{vmatrix} = 0$$

214

215 The above determinant identity is equivalent to $|\mathbf{k}_1 + \lambda(\mathbf{k}_{g1} + \mathbf{k}_{g3})| \times |\mathbf{k}_2 + \lambda(\mathbf{k}_{g2} + \mathbf{k}_{g4})| = 0$ which

216 is satisfied either when the conditions $|\mathbf{k}_1 + \lambda(\mathbf{k}_{g1} + \mathbf{k}_{g3})| = 0$ or $|\mathbf{k}_2 + \lambda(\mathbf{k}_{g2} + \mathbf{k}_{g4})| = 0$ are

217 satisfied. If the eigen-value $\lambda = \lambda_1$ satisfies the first condition $|\mathbf{k}_1 + \lambda(\mathbf{k}_{g1} + \mathbf{k}_{g3})| = 0$, Eq. (13)

218 indicates that $\mathbf{A}_a \neq \mathbf{0}$. In this case, the condition $|\mathbf{k}_2 + \lambda_1(\mathbf{k}_{g2} + \mathbf{k}_{g4})| = 0$ will, in general, be

219 violated indicating that the only solution of Eq. (14) is $\mathbf{A}_b = \mathbf{0}$. In a similar manner, if the eigen-

220 value $\lambda = \lambda_2$ satisfies the condition $|\mathbf{k}_2 + \lambda(\mathbf{k}_{g2} + \mathbf{k}_{g4})| = 0$, Eq. (14) indicates that $\mathbf{A}_b \neq \mathbf{0}$ and the

221 condition $|\mathbf{k}_1 + \lambda_2(\mathbf{k}_{g1} + \mathbf{k}_{g3})| = 0$ will, in general, be violated indicating that $\mathbf{A}_a = \mathbf{0}$. It is noted

222 that the entries of vector \mathbf{A}_a always correspond to a symmetric buckling mode while the

223 coefficients of vector \mathbf{A}_b correspond to an anti-symmetric mode (Hu 2016).

224 In summary, the solution for the eigen-value problem in Eq. (12) has two sets of possible eigen

225 values: The first set $\lambda = \lambda_1$ arises from the solution of the condition $|\mathbf{k}_1 + \lambda_1(\mathbf{k}_{g1} + \mathbf{k}_{g3})| = 0$ and

226 the corresponding eigen-vectors are $\mathbf{A}_a \neq \mathbf{0}$, $\mathbf{A}_b = \mathbf{0}$. The second set $\lambda = \lambda_2$ arises from the

227 solution of $|\mathbf{k}_2 + \lambda_2(\mathbf{k}_{g2} + \mathbf{k}_{g4})| = 0$ and the corresponding eigen vectors are $\mathbf{A}_a = \mathbf{0}$ and $\mathbf{A}_b \neq \mathbf{0}$.

228 For the special case where both conditions $|\mathbf{k}_1 + \lambda(\mathbf{k}_{g1} + \mathbf{k}_{g3})| = 0$ and $|\mathbf{k}_2 + \lambda(\mathbf{k}_{g2} + \mathbf{k}_{g4})| = 0$ are

229 satisfied, one has a repeated eigenvalue $\lambda_1 = \lambda_2$. In such a case Equations (13) and (14) indicate

230 that the conditions $\mathbf{A}_a \neq \mathbf{0}$ and $\mathbf{A}_b \neq \mathbf{0}$ are possible. Such a case is treated in detail in the section
 231 titled “Recovering the threshold bracing height”.

232
 233 **Recovering the threshold bracing height**

234 As shown in the results (e.g., Fig. 6), while the critical load corresponding to Mode 1 (symmetric)
 235 depends on the bracing height, that based on Mode 2 (anti-symmetric) is independent of it, yielding
 236 a constant critical moment value for a given beam geometry and load configuration. In contrast,
 237 the buckling moment corresponding to Mode 1 decreases as the bracing height is lowered.
 238 Conceptually, there is a threshold bracing height b_{cr} at which both modes yield the same critical
 239 moments. When the brace is above this threshold height, the member attains its maximal capacity
 240 as dictated by the anti-symmetric mode. The present section develops a methodology to recover
 241 the critical bracing height: Equation (14) is solved for the eigenvalue λ_2 , and one sets $\lambda_1 = \lambda_2$.
 242 Equation (13) is then solved for the threshold bracing height b_{cr} . From Eqs. (7), the elastic stiffness
 243 matrix \mathbf{k}_1 can be re-written as the sum of three matrices

244
$$\mathbf{k}_1 = \bar{\mathbf{k}}_1 + b_{cr} \bar{\mathbf{k}}_1 + b_{cr}^2 \bar{\mathbf{k}}_1 \quad (15)$$

245 where matrices $\bar{\mathbf{k}}_1, \bar{\mathbf{k}}_1, \bar{\mathbf{k}}_1$ are provided in Appendix B

246 Also, from Eq.(25), the geometric stiffness matrix \mathbf{k}_{g1} can be expressed as

247
$$\mathbf{k}_{g1} = \bar{\mathbf{k}}_{g1} + b_{cr} \bar{\mathbf{k}}_{g1} \quad (16)$$

248 and matrices $\bar{\mathbf{k}}_{g1}, \bar{\mathbf{k}}_{g1}$ are provided in Appendix B. From Eqs. (15) and (16), by substituting into Eq.
 249 (13), one obtains a quadratic eigenvalue problem in the unknown critical bracing height b_{cr}

250
$$\left[\left(\bar{\mathbf{k}}_1 + \lambda_2 \bar{\mathbf{k}}_{g1} + \lambda_2 \mathbf{k}_{g3} \right) + b_{cr} \left(\bar{\bar{\mathbf{k}}}_1 + \lambda_2 \bar{\bar{\mathbf{k}}}_{g1} \right) + b_{cr}^2 \bar{\bar{\bar{\mathbf{k}}}}_1 \right] \mathbf{A}_a = \mathbf{0} \quad (17)$$

251 Given λ_2 , one can recover the sought critical bracing height by solving the quadratic eigen value
 252 problem defined in Eq. (17).

253 **Verification Example**

254 To verify the validity of the model, the critical moments of a reference beam as predicted by the
 255 present model are compared to those based on a 3D FEA eigen-value buckling analyses based on
 256 the commercial software ABAQUS for various bracing heights. The reference beam has a width
 257 $w = 130mm$, a height $h = 950mm$ and a span of $13,000mm$. For a rectangular section of width
 258 w and depth h , $I_{yy} = hw^3 / 12 = 1.74 \times 10^8 mm^4$, $C_w = w^3 h^3 / 144 = 1.31 \times 10^{13} mm^6$ and the Saint-
 259 Venant torsional constant as given in the detailed method of Pai (2007) is $J = 6.36 \times 10^8 mm^4$.
 260 Material is assumed to be glued-laminated timber, Spruce-Lodgepole Pine with 20f-EX grade. The
 261 modulus of elasticity in the longitudinal direction is taken as $E = E_L = 10,300MPa$ (CSA O86
 262 2014) and shear modulus is $G = G_{LT} = G_{LR} = 474MPa$ (FPL 2010).

263 **Convergence study of present model**

264 To determine the number of Fourier terms n needed for convergence, a convergence study was
 265 conducted on 20 cases with different load configurations (uniformly distributed, mid-span point
 266 loads), brace heights $b/h = -0.5, 0.0, 0.5$ and load heights $a/h = -0.5, 0.0, 0.5$. Detailed
 267 descriptions and results from the convergence study can be found in (Hu 2016). The ratio of critical
 268 moments based on $n = 4$ to those based on $n = 6$ where shown to be less than 0.63% in all 20
 269 cases considered. Given that the computational time involved is nearly instantaneous, the number
 270 of modes n was conservatively set to 9 in subsequent runs, (i.e., 18 Fourier terms were taken in
 271 Eqs. (3) and (4)).

272 **The 3D finite element model**

273 The C3D8 brick element in ABAQUS was used to discretize the beam. The C3D8 element is three-
274 dimensional continuum elements in ABAQUS consisting of 8 nodes at the corners and 24 degrees
275 of freedom in total (three translations at each node) (Simulia, 2011). This type of element uses
276 linear interpolation in each direction. An orthotropic material model is adopted to represent the
277 wood properties. In a manner consistent with the work of Xiao (2014) and Xiao et al. (2014), the
278 modulus of elasticity in the longitudinal direction is taken as $E_L = 10300MPa$ and the moduli of
279 elasticity in the tangential and radial directions were taken as $E_T = E_R = 700MPa$. The shear
280 moduli are taken as $G_{LR} = G_{LT} = 474MPa$ and $G_{RT} = 51.5MPa$ and the Poisson's ratios are taken
281 as $\nu_{LR} = \nu_{LT} = 0.347$ and $\nu_{RT} = 0.469$. To simulate simply supported boundary conditions at both
282 ends relative to pre-buckling transverse displacements (i.e., $v(0) = v(L) = 0$) and buckling twist
283 and lateral deflections (i.e., $u(0) = \theta(0) = u(L) = \theta(L) = 0$) while keeping free the strong axis
284 rotations $v'(0) \neq 0, v'(L) \neq 0$, weak axis rotations, and warping deformations
285 $\theta'(0) \neq 0, \theta'(L) \neq 0$ in a manner consistent with the model developed in the present study, two
286 groups of restraints were enforced at both ends of the model: (1) As shown in Fig. 3, a set of
287 constraints related to vertical displacements were imposed along axes AB and $A'B'$ at the end
288 cross sections. For axes CD and $C'D'$, the lateral displacements were restrained by imposing
289 another group of constraints. (2) The centroid of the cross section at one end was longitudinally
290 restrained (Fig.3a), while that at the other end was left free to move longitudinally (Fig.3b). The
291 mid-span lateral brace was simulated by retraining the lateral displacement at the node located at
292 the target bracing height on the mid-span vertical line passing through the section centroid. A mesh
293 sensitivity analysis was conducted on 12 cases with different load configurations (uniformly

294 distributed, mid-span point loads), brace heights $b/h = -0.5, 0.0, 0.5$ and load heights
295 $a/h = -0.5, 0.0, 0.5$. The governing modes were symmetric in some of the runs and anti-symmetric
296 in other runs. The results (Hu 2016) showed that critical moment predictions based on 410
297 elements longitudinally, 50 elements along the height, 10 elements along the width do not change
298 by more than 0.08% when finer meshes are taken. Thus, a 410x50x10 mesh will be taken in
299 subsequent runs.

300 **Comparison of critical moments and buckling modes**

301 Three sets of comparisons were conducted by varying bracing height with different load height
302 cases (i.e. top face, mid-height, and bottom face) between the results of formulation developed in
303 the present study and those based on the ABAQUS model. The buckling load magnitudes obtained
304 from the two solutions are overlaid in Fig. 4. Both models predict two types of buckling modes:
305 symmetric and anti-symmetric. The anti-symmetric mode is associated with a critical moment
306 value that is independent of the bracing height while critical moment based on the symmetric mode
307 is found to depend on the bracing height. Fig. 4 shows close agreement between the predictions of
308 the present study and those of the ABAQUS simulations. Percentage differences were found to be
309 within 1.09%-4.08% (Hu 2016). The buckling load values obtained from the present study are
310 slightly higher than those obtained from the ABAQUS simulation. The difference is due to the fact
311 that the present model is based on the simplifying kinematic assumptions that neglect distortional
312 and shear deformation effects and thus provides a slightly higher representation of the beam
313 stiffness than the ABAQUS model which allows distortion and shear deformations effects. The
314 symmetric and anti-symmetric buckling modes are compared to ABAQUS 3D results (Fig. 5) for
315 the cases of point load and uniformly distributed load for the cases

316 $(a/h, b/h) = (0,0), (0.5,0), (0,0.5), (0.5,0.5)$. Close agreement is observed between the present
317 model and those based on the ABAQUS simulations.

318 **Parametric study**

319 A parametric study was conducted by varying the bracing height and load heights (i.e. top face,
320 mid-height and bottom face) for point load and uniformly distributed load cases (Fig. 6). The
321 buckling load corresponding to the anti-symmetric mode (Mode 2) is observed to be independent
322 of the bracing height. For both loading cases, the buckling load for Mode 1 decreases when the
323 lateral brace is moved downwards. Also, for both loading cases, the buckling load corresponding
324 Mode 1 decreases with load height increase. For Mode 2, the buckling load is observed to be
325 independent of load height for the case of point load but found to decrease with load height increase
326 for the case of uniformly distributed load.

327 **Development of Simplified design expressions**

328 A database of 148 runs (Hu 2016) was developed to investigate the effect of various geometric
329 and elastic properties on threshold bracing height and the critical moment. Of the 148 cases, 68
330 runs investigated the case of point load and 80 runs were conducted for the case of uniformly
331 distributed load. Ranges of material properties were chosen to conform to those provided in CSA
332 O86 (2014) and (FPL, 2010). The ranges of parameters investigated are $0.137 \leq w/h \leq 0.856$,
333 $8.42 \leq L/h \leq 21.05$, and $1/10 \leq G/E \leq 1/20$. Subsequently, approximate design expressions were
334 developed based on regressing analysis.

335 **Point load**

336 The relationship between the critical bracing height to section height ratio \bar{b}_{cr}/h and the parameters
 337 $w/h, L/h, a/h, G/E$ were found to exhibit a nearly linear dependence (Hu 2016). Therefore, the
 338 approximate critical height ratio \bar{b}_{cr}/h was postulated to take the form

$$339 \quad \left(\frac{\bar{b}_{cr}}{h} \right) \approx \alpha_0 + \alpha_1 \left(\frac{w}{h} \right) + \alpha_2 \left(\frac{L}{h} \right) + \alpha_3 \left(\frac{a}{h} \right) + \alpha_4 \left(\frac{G}{E} \right) \quad (18)$$

340 where $\alpha_0, \alpha_1, \alpha_2, \alpha_3, \alpha_4$ are coefficients to be determined from the regression analysis. The sum
 341 of the squares of the differences between the values of (b_{cr}/h) as obtained by the present solution
 342 and that based on the expression in Eq. (18) is minimized, i.e.,

$$343 \quad D_1 = \sum_{i=1}^m \left[\left(\frac{\bar{b}_{cr}}{h} \right) - \left(\frac{b_{cr}}{h} \right) \right]_i^2 = \min \quad (19)$$

344 where m is the number of runs conducted, by enforcing the minimization conditions
 345 $\partial D_1 / \partial \alpha_i = 0$ ($i = 0, 1, \dots, 4$) yielding the regression constants $\alpha_0 = 0.08089, \alpha_1 = 0.07364$,
 346 $\alpha_2 = -0.01529, \alpha_3 = 0.6870, \alpha_4 = -1.5130$. The domain validity of the regression coefficients is
 347 that of the database of runs, i.e., $0.137 \leq w/h \leq 0.856, 8.42 \leq L/h \leq 21.05$, and $1/10 \leq G/E \leq 1/20$.
 348 Within these domains, the standard deviation of the difference between the predictions of the
 349 regression equation \bar{b}_{cr}/h to that of the present solution was found to be 0.0041. When the bracing
 350 height b is greater than the critical bracing height b_{cr} (or \bar{b}_{cr} as estimated by Eq.(18)), the critical
 351 moment will be maximized and will attain that based on the anti-symmetric mode. Under this
 352 mode, the lateral displacement and angle of twist vanish at beam mid-span and the unsupported
 353 length is $L_u = L/2$. The corresponding critical moment M_{cr} is then given by

354
$$\bar{M}_{cr} \approx C_b \frac{\pi}{L_u} \sqrt{EI_{yy}GJ + \left(\frac{\pi E}{L_u}\right)^2 I_{yy}C_w} \quad (20)$$

355 where C_b is a moment gradient factor within the beam half-span. Given the critical moment values
 356 M_{cr} based on the present analysis (Hu 2016) and knowing E, I_{yy}, G, J, C_w and L_u , the moment
 357 gradient factor C_b is determined for each run. The procedure was repeated for all 68 runs and was
 358 found to range from 1.78 to 1.81 with an average value of 1.80 and a standard deviation of 0.008.
 359 The value $C_b = 1.80$ obtained is in line with that based on quarter point formulas of the AFPA
 360 (2003) of 1.67, CAN-CSA S16 (2014) of 1.74, and, AS4100 (1998) of 1.82.

361 **Uniformly distributed load**

362 The approximate critical height ratio \bar{b}_{cr}/h was postulated to take the form

363
$$\left(\frac{\bar{b}_{cr}}{h}\right) \approx \beta_0 + \beta_1\left(\frac{w}{h}\right) + \beta_2\left(\frac{L}{h}\right) + \beta_3\left(\frac{a}{h}\right) + \beta_4\left(\frac{a}{h}\right)^2 + \beta_5\left(\frac{G}{E}\right) \quad (21)$$

364 where m is the number of runs conducted (Hu 2016) by enforcing the conditions
 365 $\partial D_1/\partial \beta_i = 0 \quad i = 0, 1, 2, \dots, 5$ yielding the regression constants $\beta_0 = 0.1740$, $\beta_1 = 0.1368$,
 366 $\beta_2 = -0.02950$, $\beta_3 = 0.2944$, $\beta_4 = 0.1595$, $\beta_5 = -2.9995$. The domain validity of the regression
 367 coefficients is $0.137 \leq w/h \leq 0.856$, $-0.5 \leq a/h \leq 0.5$, $8.42 \leq L/h \leq 15.79$, $1/10 \leq G/E \leq 1/20$.

368 Within these domains, the standard deviation of the difference between the predictions of the
 369 regression equation \bar{b}_{cr}/h to that of the present solution was found to be 0.0066. When the bracing
 370 height is greater than the critical bracing height b_{cr} or \bar{b}_{cr} as estimated by Eq. (21), the buckling
 371 capacity will be maximized and will attain the critical moment of the anti-symmetric mode. Under
 372 this mode, the lateral displacement and angle of twist vanish at mid-span. Under these conditions,

373 the unsupported length is $L_u = L/2$. As the critical moments based on the anti-symmetric mode
 374 changes with the load height position (e.g., Fig. 6), additional terms to capture the load height
 375 effect should be added to the approximate function. The results of database of runs have shown
 376 that the difference between the critical moments for mid-height loading and those based on loading
 377 acting at height a above the centroid are nearly proportional to the term aEI_{yy}/L_u^2 . As such, the
 378 following equation was proposed to estimate the critical moments including load height effects
 379 (Hu 2016):

$$380 \quad \bar{M}_{cr} = C_b \frac{\pi}{L_u} \sqrt{EI_{yy}GJ + \left(\frac{\pi E}{L_u}\right)^2 I_{yy}C_w} - C_e \frac{aEI_{yy}}{L_u^2} \quad (22)$$

381 The sum of the squares of the differences between the values of the buckling capacity obtained by
 382 the present solution (Hu 2016) and that based on (22) is minimized, i.e.

$$383 \quad D_2 = \sum_{i=1}^m \left[\bar{M}_{cr} - M_{cr} \right]_i^2 = \min \quad (23)$$

384 The minimization process yields the moment gradient factor $C_b = 1.32$ and the load position
 385 modifier $C_e = 1.68$. The average value of C_b is consistent with that based on CAN-CSA S16
 386 (2014) of 1.32, AFPA (2003) of 1.30, and AS4100 (1998) of 1.33.

387 **Assessment of threshold bracing height predicted by simplified equations**

388 In order to assess the accuracy of the threshold bracing height predictions based on the simplified
 389 equations, comparisons are made against 3D FEA results for cases outside the database of runs
 390 used to produce the regression results. Two loading cases are considered: mid-span point load and
 391 uniformly distributed load. In both cases four loading height are examined:
 392 $a/h = -0.25, 0, 0.25, 0.50$. For the point load case, a simply supported glulam beam with a
 393 rectangular cross-section of depth $h = 570mm$, width $w = 130mm$ and a span = $11,500mm$ and

394 sectional and material properties $J = 3.57 \times 10^8 \text{ mm}^4$, $I_{yy} = 1.04 \times 10^8 \text{ mm}^4$, $C_w = 2.83 \times 10^{12} \text{ mm}^6$,
395 $E = 10,300 \text{ MPa}$ and $G = 515 \text{ MPa}$. For the uniformly distributed load cases, a simply supported
396 glulam beam with a rectangular cross-section of depth $h = 798 \text{ mm}$, width $w = 215 \text{ mm}$ and a span=
397 $10,000 \text{ mm}$ is taken with sectional and material properties are $J = 2.19 \times 10^9 \text{ mm}^4$,
398 $I_{yy} = 6.61 \times 10^8 \text{ mm}^4$, $C_w = 3.51 \times 10^{13} \text{ mm}^6$, $E = 10,300 \text{ MPa}$ and $G = 644 \text{ MPa}$. It is required to
399 determine the threshold bracing height b_{cr}/h in each case based on the simplified expressions and
400 based on ABAQUS. In the case of ABAQUS solution, multiple runs are conducted with different
401 bracing heights in order to identify the threshold bracing height where the symmetric and anti-
402 symmetric modes provide identical critical moments. The results in Table 1 indicate that
403 predictions of both methods agree within 5% of the section height.

404 **Design Example 1- Beam under mid-span point load**

405 A simply supported glulam beam with a rectangular cross-section of depth $h = 570 \text{ mm}$, width
406 $w = 130 \text{ mm}$ and a span= $11,500 \text{ mm}$ is subjected to a mid-span point load acting at top of the
407 cross section. The beam is laterally braced at mid-span. Two bracing heights are considered: (a)
408 200 mm and (b) 0 mm . Sectional and material properties are $J = 3.57 \times 10^8 \text{ mm}^4$,
409 $I_{yy} = 1.04 \times 10^8 \text{ mm}^4$, $C_w = 2.83 \times 10^{12} \text{ mm}^6$, $E = 10,300 \text{ MPa}$ and $G = 515 \text{ MPa}$. It is required to
410 determine the critical moment.

411 **Threshold bracing height check:**

412 For the present problem, one has $w/h = 0.228$, $L/h = 20.2$, $a/h = 0.5$ and $G/E = 1/20$. These ratios
413 meet the applicability conditions for Eq.(18). The threshold bracing height ratio as computed from
414 Eq. (18) is $\bar{b}_{cr}/h = 0.057$. This compares to $b_{cr}/h = 0.073$ as predicted by the detailed procedure
415 in Eq. (17), a 0.02 difference. Thus, a bracing height above $0.057 \times 570 = 33 \text{ mm}$ is deemed high
20

416 enough to fully restrain the angle of twist at mid-span and maximize the critical moments by
417 forcing the beam to buckle in an anti-symmetric mode. This condition is satisfied for Case a where
418 the bracing height is $200mm > 33mm$ but not in Case b for a bracing height of $0mm < 33mm$.

419 **Critical moment for case (a)**

420 Since $w/h, L/h, a/h, G/E$ lie within the domain of applicability of the regression equation, the
421 simplified moment calculation in Eq. (20) is applied. As discussed, when twist and lateral
422 displacements vanish at mid-span, the mid-span point is considered as a point of full lateral and
423 torsional restraint and the unbraced length becomes $L_u = L/2 = 5,750mm$. The critical moment
424 \bar{M}_{cr} as determined from Eq. (20) is found to be $447kNm$. This value compares to $444kNm$ as
425 predicted by the present formulation, a 0.69% difference, and $437kNm$ as predicted by the 3D
426 ABAQUS model, a 2.23% difference.

427 **Critical moment for case (b)**

428 For zero bracing height, the mid-span section will be only partially restrained from twisting, and
429 the beam capacity will be governed by the symmetric buckling mode. Under this scenario, the
430 critical moment can no longer be calculated using the simplified Eq. (20) and a detailed analysis
431 based on the present formulation would be needed. The critical moment is found to be
432 $M_{cr} = 411kNm$, which compares to $397kNm$ based on the ABAQUS 3D model. As expected, the
433 critical moment is smaller compared to that of Case (a). A lower bound for the critical moment in
434 case (b) can be obtained by entirely omitting the bracing effect at mid-span. Under this scenario,
435 $L_u = L = 11,500mm$ and moment gradient C_b based on the AFPA (2003) recommendations is
436 1.33. Comparable values are obtained from CAN-CSA S16 (2014) which yields 1.26, or AS4100
437 (1998) which yields 1.39. For a point load applied at the top of the cross-section, the AFPA (2003)

438 load eccentricity factor is given by $C_e = \sqrt{\eta^2 + 1} - \eta$ where $\eta = (k^* h / 2L_u) \sqrt{EI_{yy} / GJ}$ where
439 $k^* = 1.72$ for the case of point loading, yielding $C_e = 0.815$. The sought lower bound of the
440 critical moment is given by $M_{cr} = (C_e C_b \pi / L_u) \sqrt{EI_{yy} GJ + (\pi E / L_u)^2 I_{yy} C_w}$ yielding $M_{cr} = 132 kNm$.
441 In summary, the critical moment of $411 kNm$ based on the detailed procedure is significantly
442 higher than the critical moment based on no intermediate support restraint but slightly less than
443 the critical moment of $444 kNm$ based on the case of full bracing.

444 **Example 2 – Beam under a uniformly distributed load**

445 A simply supported glulam beam with rectangular section of depth $h = 798 mm$, width $w = 215 mm$
446 is spanning $10,000 mm$. The beam is subjected to a uniformly distributed load acting at the top
447 face of the beam. The beam is laterally braced at mid-span. Sectional and material properties are:
448 $J = 2.19 \times 10^9 mm^4$, $I_{yy} = 6.61 \times 10^8 mm^4$, $C_w = 3.51 \times 10^{13} mm^6$, $E = 10,300 MPa$ and
449 $G = 644 MPa$. Two bracing heights are considered: (a) $100 mm$ and (b) $-300 mm$ (the negative
450 sign indicates that the bracing is located below the section mid-height). It is required to determine
451 the critical moment capacity.

452 The dimensionless ratios $w/h = 0.27$, $L/h = 12.5$, $a/h = 0.5$ and $G/E = 1/16$ are within the
453 applicability limits of the threshold bracing height and critical moment equations. The threshold
454 bracing height ratio as determined from Eq. (21) is $\bar{b}_{cr} / h = -0.158$. This compares to -0.157
455 based on the detailed procedure, a 0.002 difference. Thus, a bracing height above
456 $-0.158 \times 798 = -126.1 mm$ is deemed high enough to fully restrain the angle of twist at mid-span.
457 This happens to be the case for a bracing height of $100 mm$ (Case a), but is not for a bracing height
458 of $-300 mm$ (Case b). The unbraced length is $L_u = L/2 = 5,000 mm$ and the critical moment based

459 on Eq. (22) is found to be $252kNm$. This value compares to $253kNm$ as predicted by the detailed
460 procedure provided, a 0.050% difference.

461 When the bracing height is $-300mm$, the mid-span section will only be partially restrained from
462 twisting and the beam critical moment based on the detailed analysis is found to be $M_{cr} = 171kNm$.

463 As expected, the critical moment is found smaller than that based on Case (a). A lower bound for
464 the critical moment in case (b) can be obtained based on an unsupported length
465 $L_u = L = 10,000mm$ and the moment gradient C_b is determined as 1.13 from the AFPA

466 recommendations (2003), and a load eccentricity factor One can also apply the $C_e = \sqrt{\eta^2 + 1} - \eta$

467 (AFPA 2003) where $\eta = \left(k^* h/2L_u\right) \sqrt{EI_{yy}/GJ}$ and $k^* = 1.44$ for uniformly distributed load,

468 yielding a value $C_e = 0.779$. The corresponding critical moment is

469 $M_{cr} = \left(C_e C_b \pi/L_u\right) \sqrt{EI_{yy} GJ + \left(\pi E/L_u\right)^2 I_{yy} C_w} = 101kNm$. This lower bound is again significantly

470 lower than the critical moment obtained by the present detailed solution.

471 **Summary and conclusions**

472 Analytical solutions were developed for the lateral torsional buckling analysis of simply supported
473 wooden beams with discrete lateral supports at mid-span subjected to symmetric moment load
474 distributions relative to mid-span. The model accounts for the combined effect of eccentricities of
475 the bracing and the loads. The models were validated against a 3D FEA solutions and parametric
476 study to investigate the influence of mid-span bracing height and load height was conducted. The
477 conclusions can be summarized as follows:

478 1. The model predicts two possible buckling modes: symmetric and anti-symmetric, depending on
479 the load height and bracing height. The anti-symmetric mode in the present study is indirectly
480 promoted by the prescriptive requirements for lumber joists in CAN-CSA O86 (2014) and NDS
23

481 (2015) which stipulate cross-bridging or full-height blocking to achieve full twist restraint at the
482 point of brace. Such restraints would suppress the symmetric buckling mode and promote an anti-
483 symmetric buckling mode identical to that obtained in the present study. The present study
484 achieves full twist in a different manner by locating the lateral brace above the critical threshold
485 bracing height.

486 2. For a given load height, simple expressions were developed for determining the threshold
487 bracing height at which the capacity is governed by the antisymmetric mode.

488 3. For point load and uniformly distributed load, critical moments based on the symmetric mode
489 are observed to decrease when the load height increases

490 4. For point load loading, critical moments based on the anti-symmetric modes are found to be
491 independent from the load height. In contrast, for uniformly distributed loads, they are found to
492 decrease as the point of application of the load moves upwards.

493 5. For mid-span point loading, the threshold bracing height normalized relative to cross section
494 height b_{cr}/h was observed correlate nearly linearly with geometric and elastic parameters a/h , L/h ,
495 w/h and G/E .

496 6. For uniformly distributed loading, the normalized threshold bracing height b_{cr}/h was observed
497 to have a nearly linear correlation with geometric and parameters a/h , w/h and G/E , while
498 having a nearly quadratic correlation with L/h .

499 7. Simplified design equations were developed to reliably estimate the threshold bracing height
500 required to maximize the critical moments and quantify the critical moments for cases where the
501 bracing location is above the threshold height as computed by the simplified equation.

502

503 **Appendix A: Formulation of geometric matrices**

504 **Destabilizing term due to bending moments**

505 From Eqs.(4), (5) and (9)a, by substituting into Eq. (2)a, one obtains the load potential energy
 506 function as

507
$$V_1 = \frac{\lambda}{2} \langle \mathbf{A}_a^T \quad \mathbf{A}_b^T \rangle \begin{bmatrix} \mathbf{k}_{g1} & \mathbf{k}_{g12}^T \\ \mathbf{k}_{g12}^T & \mathbf{k}_{g2} \end{bmatrix} \begin{Bmatrix} \mathbf{A}_a \\ \mathbf{A}_b \end{Bmatrix} \quad (24)$$

508 where

$$\mathbf{k}_{g1} = \begin{bmatrix} \mathbf{n}_{1,1} & \mathbf{n}_{1,3} & \cdots & \mathbf{n}_{1,2i-1} & \cdots & \mathbf{n}_{1,2n-1} \\ \mathbf{n}_{3,1} & \mathbf{n}_{3,3} & \cdots & \mathbf{n}_{3,2i-1} & \cdots & \mathbf{n}_{3,2n-1} \\ \vdots & \vdots & \ddots & \vdots & \ddots & \vdots \\ \mathbf{n}_{2j-1,1} & \mathbf{n}_{2j-1,3} & \cdots & \mathbf{n}_{2j-1,2i-1} & \cdots & \mathbf{n}_{2j-1,2n-1} \\ \vdots & \vdots & \ddots & \vdots & \ddots & \vdots \\ \mathbf{n}_{2n-1,1} & \mathbf{n}_{2n-1,3} & \cdots & \mathbf{n}_{2n-1,2i-1} & \cdots & \mathbf{n}_{2n-1,2n-1} \end{bmatrix}, \mathbf{k}_{g2} = \begin{bmatrix} \mathbf{n}_{2,2} & \mathbf{n}_{2,4} & \cdots & \mathbf{n}_{2,2i} & \cdots & \mathbf{n}_{2,2n} \\ \mathbf{n}_{4,2} & \mathbf{n}_{4,4} & \cdots & \mathbf{n}_{4,2i} & \cdots & \mathbf{n}_{4,2n} \\ \vdots & \vdots & \ddots & \vdots & \ddots & \vdots \\ \mathbf{n}_{2j,2} & \mathbf{n}_{2j,4} & \cdots & \mathbf{n}_{2j,2i} & \cdots & \mathbf{n}_{2j,2n} \\ \vdots & \vdots & \ddots & \vdots & \ddots & \vdots \\ \mathbf{n}_{2n,2} & \mathbf{n}_{2n,4} & \cdots & \mathbf{n}_{2n,2i} & \cdots & \mathbf{n}_{2n,2n} \end{bmatrix}$$

$$\mathbf{K}_{g12} = \begin{bmatrix} \mathbf{n}_{1,2} & \mathbf{n}_{1,4} & \cdots & \mathbf{n}_{1,2i} & \cdots & \mathbf{n}_{1,2n} \\ \mathbf{n}_{3,2} & \mathbf{n}_{3,4} & \cdots & \mathbf{n}_{3,2i} & \cdots & \mathbf{n}_{3,2n} \\ \vdots & \vdots & \ddots & \vdots & \ddots & \vdots \\ \mathbf{n}_{2j-1,2} & \mathbf{n}_{2j-1,4} & \cdots & \mathbf{n}_{2j-1,2i} & \cdots & \mathbf{n}_{2j-1,2n} \\ \vdots & \vdots & \ddots & \vdots & \ddots & \vdots \\ \mathbf{n}_{2n-1,2} & \mathbf{n}_{2n-1,4} & \cdots & \mathbf{n}_{2n-1,2i} & \cdots & \mathbf{n}_{2n-1,2n} \end{bmatrix}, \mathbf{n}_{j,i} = \begin{bmatrix} 0 & m_{5,i,j} \\ m_{6,i,j} & 0 \end{bmatrix} + b \begin{bmatrix} 0 & 0 \\ 0 & m_{7,i,j} \end{bmatrix}$$

509
 510 (25)a-d

511
$$\begin{aligned} m_{5,i,j} &= -\frac{(j\pi)^2}{L} \beta(j,i,k_{max}) + (-1)^n \left(\frac{1}{L}\right) [(2n+1)\pi]^2 \sin \frac{j\pi}{2} \beta(2n+1,i,k_{max}) \\ m_{6,i,j} &= -\frac{(i\pi)^2}{L} \beta(i,j,k_{max}) + (-1)^n \left(\frac{1}{L}\right) [(2n+1)\pi]^2 \sin \frac{i\pi}{2} \beta(2n+1,j,k_{max}) \\ m_{7,i,j} &= (-1)^n \left(\frac{1}{L}\right) [(2n+1)\pi]^2 \beta(2n+1,j,k_{max}) \sin \frac{i\pi}{2} \\ &\quad + (-1)^n \left(\frac{1}{L}\right) [(2n+1)\pi]^2 \beta(2n+1,i,k_{max}) \sin \frac{j\pi}{2} \end{aligned} \quad (26)$$

512
$$\beta(i, j, k_{max}) = \frac{1}{L} \int_0^L \sum_{k=1,2}^{k_{max}} m_k \sin \frac{i\pi z}{L} \sin \frac{j\pi z}{L} \sin \frac{k\pi z}{L} dz \quad (27)$$

513 **Special considerations for symmetric loading**

514 For loading symmetric with respect to $z = L/2$, bending moments are symmetric and Eq. (9)
 515 yields

516
$$M(z) = \sum_{k=1,3,5}^{k_{max}} m_k \sin \frac{k\pi z}{L} \quad (28)$$

517 where k takes only the values 1,3,5... Thus, when one of i, j is odd and the other is even, matrix
 518 $\mathbf{n}_{j,i}$ as defined in Eq. (25) can be shown to vanish. This is the case since function
 519 $\sin(i\pi z/L) \sin(j\pi z/L)$ is anti-symmetric with respect to $z = L/2$ and

520 $\sum_{k=1,2}^{k_{max}} m_k \sin(i\pi z/L) \sin(j\pi z/L) \sin(k\pi z/L)$ in Eq. (27) is also anti-symmetric and

521
$$\beta(i, j, k_{max}) = \frac{1}{L} \int_0^L \sum_{k=1,2}^{k_{max}} m_k \sin \frac{i\pi z}{L} \sin \frac{j\pi z}{L} \sin \frac{k\pi z}{L} dz = 0 \quad (29)$$

522 Also, for the case where one of i, j is odd and the other is even, one can show that

523
$$\sin \frac{j\pi}{2} \beta(2n+1, i, k_{max}) = \sin \frac{i\pi}{2} \beta(2n+1, j, k_{max}) = 0 \quad (30)$$

524 From Eq. (29) and (30) by substituting into Eq.(26), one has $\mathbf{n}_{j,i} = \mathbf{0}$ when one of i, j is odd and
 525 the other is even and thus $\mathbf{k}_{g12} = \mathbf{0}$, and Eq. (24) takes the form

526
$$V_1 = \frac{\lambda}{2} \langle \mathbf{A}_a^T \quad \mathbf{A}_b^T \rangle \begin{bmatrix} \mathbf{k}_{g1} & \mathbf{0} \\ \mathbf{0} & \mathbf{k}_{g2} \end{bmatrix} \begin{Bmatrix} \mathbf{A}_a \\ \mathbf{A}_b \end{Bmatrix} \quad (31)$$

527 **Destabilizing term due to load height effect**

528 *Case1- Mid-span load offset from section mid-height*

529 A mid-span point load λQ can be mathematically expressed as $\lambda q(z) = \lambda Q \delta(z - L/2)$ where
 530 δ is the Dirac Delta function. If the load is acting at a distance a above the section mid-height,
 531 the load potential energy gain V_2 as determined from in Eq. (2)b takes the form

532
$$V_2 = -\frac{\lambda}{2} \int_0^L Q \delta\left(z - \frac{L}{2}\right) a \theta(z)^2 dz = -\frac{\lambda}{2} Q a \theta\left(\frac{L}{2}\right)^2 = -\frac{\lambda}{2} Q a \sum_{i=1,2}^{2n} \sum_{j=1,2}^{2n} B_i B_j \sin\left(\frac{i\pi}{2}\right) \sin\left(\frac{j\pi}{2}\right) \quad (32)$$

533 In a matrix form, V_2 can be expressed as

534
$$V_2 = \frac{\lambda}{2} \langle \mathbf{A}_a^T \quad \mathbf{A}_b^T \rangle \begin{bmatrix} \mathbf{k}_{g3} & \mathbf{k}_{g34} \\ \mathbf{k}_{g34}^T & \mathbf{k}_{g4} \end{bmatrix} \begin{Bmatrix} \mathbf{A}_a \\ \mathbf{A}_b \end{Bmatrix} \quad (33)$$

535 where

536
$$\mathbf{k}_{g3} = Qa \begin{bmatrix} \mathbf{r}_{1,1} & \mathbf{r}_{1,3} & \cdots & \mathbf{r}_{1,2i-1} & \cdots & \mathbf{r}_{1,2n-1} \\ \mathbf{r}_{3,1} & \mathbf{r}_{3,3} & \cdots & \mathbf{r}_{3,2i-1} & \cdots & \mathbf{r}_{3,2n-1} \\ \vdots & \vdots & \ddots & \vdots & \ddots & \vdots \\ \mathbf{r}_{2j-1,1} & \mathbf{r}_{2j-1,3} & \cdots & \mathbf{r}_{2j-1,2i-1} & \cdots & \mathbf{r}_{2j-1,2n-1} \\ \vdots & \vdots & \ddots & \vdots & \ddots & \vdots \\ \mathbf{r}_{2n-1,1} & \mathbf{r}_{2n-1,3} & \cdots & \mathbf{r}_{2n-1,2i-1} & \cdots & \mathbf{r}_{2n-1,2n-1} \end{bmatrix}, \mathbf{k}_{g4} = Qa \begin{bmatrix} \mathbf{r}_{2,2} & \mathbf{r}_{2,4} & \cdots & \mathbf{r}_{2,2i} & \cdots & \mathbf{r}_{2,2n} \\ \mathbf{r}_{4,2} & \mathbf{r}_{4,4} & \cdots & \mathbf{r}_{4,2i} & \cdots & \mathbf{r}_{4,2n} \\ \vdots & \vdots & \ddots & \vdots & \ddots & \vdots \\ \mathbf{r}_{2j,2} & \mathbf{r}_{2j,4} & \cdots & \mathbf{r}_{2j,2i} & \cdots & \mathbf{r}_{2j,2n} \\ \vdots & \vdots & \ddots & \vdots & \ddots & \vdots \\ \mathbf{r}_{2n,2} & \mathbf{r}_{2n,4} & \cdots & \mathbf{r}_{2n,2i} & \cdots & \mathbf{r}_{2n,2n} \end{bmatrix}$$

537
$$\mathbf{k}_{g34} = Qa \begin{bmatrix} \mathbf{r}_{1,2} & \mathbf{r}_{1,4} & \cdots & \mathbf{r}_{1,2i} & \cdots & \mathbf{r}_{1,2n} \\ \mathbf{r}_{3,2} & \mathbf{r}_{3,4} & \cdots & \mathbf{r}_{3,2i} & \cdots & \mathbf{r}_{3,2n} \\ \vdots & \vdots & \ddots & \vdots & \ddots & \vdots \\ \mathbf{r}_{2j-1,2} & \mathbf{r}_{2j-1,4} & \cdots & \mathbf{r}_{2j-1,2i} & \cdots & \mathbf{r}_{2j-1,2n} \\ \vdots & \vdots & \ddots & \vdots & \ddots & \vdots \\ \mathbf{r}_{2n-1,2} & \mathbf{r}_{2n-1,4} & \cdots & \mathbf{r}_{2n-1,2i} & \cdots & \mathbf{r}_{2n-1,2n} \end{bmatrix}, \mathbf{r}_{j,i} = \begin{bmatrix} 0 & \cdots & 0 \\ \vdots & \ddots & \vdots \\ 0 & \sin \frac{i\pi}{2} & \sin \frac{j\pi}{2} \end{bmatrix} \quad (34)$$

538 when either of i, j are even and the other is odd, the expression $\sin(i\pi/2)\sin(j\pi/2)$ vanishes.

539 In this case, matrix \mathbf{k}_{g34} vanishes and

540
$$V_2 = \frac{\lambda}{2} \langle \mathbf{A}_a^T \quad \mathbf{A}_b^T \rangle \left[\begin{array}{cc} \mathbf{k}_{g3} & \mathbf{0} \\ \mathbf{0} & \mathbf{k}_{g4} \end{array} \right]_{(1)} \begin{Bmatrix} \mathbf{A}_a \\ \mathbf{A}_b \end{Bmatrix} \quad (35)$$

541 *Case2- Uniformly Distributed load offset from section mid-height*

542 For the case of uniformly distributed load applied at height a above the section mid-height, the
 543 load potential gain can be expressed as

544
$$V_2 = -\frac{\lambda}{2} \int_0^L qa\theta(z)^2 dz = -\frac{\lambda}{2} qa \int_0^L \sum_{i=1,2}^{2n} \sum_{j=1,2}^{2n} B_i B_j \sin\left(\frac{i\pi z}{L}\right) \sin\left(\frac{j\pi z}{L}\right) dz$$

$$= \frac{\lambda}{2} \langle \mathbf{A}_a^T \quad \mathbf{A}_b^T \rangle \left[\begin{array}{cc} \mathbf{k}_{g3} & \mathbf{0} \\ \mathbf{0} & \mathbf{k}_{g4} \end{array} \right]_{(2)} \begin{Bmatrix} \mathbf{A}_a \\ \mathbf{A}_b \end{Bmatrix} \quad (36)$$

545 where

546
$$\mathbf{k}_{g3} = \mathbf{k}_{g4} = -\frac{1}{2} qLa \mathbf{Diag}(0,1,0,1\dots,0,1) \quad (37)$$

547

548 **Appendix B: Elastic and Geometric Matrices needed to determine critical bracing height.**

549 As given by Eq. (15), the elastic stiffness matrix \mathbf{k}_1 can be re-written as the sum of three matrices

550 $\mathbf{k}_1 = \bar{\mathbf{k}}_1 + b_{cr} \bar{\bar{\mathbf{k}}}_1 + b_{cr}^2 \bar{\bar{\bar{\mathbf{k}}}}_1$

551 where

552 $\bar{\bar{\bar{\mathbf{k}}}}_1 = \begin{bmatrix} \mathbf{m}''_{1,1} & \mathbf{m}''_{1,3} & \cdots & \mathbf{m}''_{1,2i-1} & \cdots & \mathbf{m}''_{1,2n-1} \\ \mathbf{m}''_{3,1} & \mathbf{m}''_{3,3} & \cdots & \mathbf{m}''_{3,2i-1} & \cdots & \mathbf{m}''_{3,2n-1} \\ \vdots & \vdots & \ddots & \vdots & \ddots & \vdots \\ \mathbf{m}''_{2j-1,1} & \mathbf{m}''_{2j-1,3} & \cdots & \mathbf{m}''_{2j-1,2i-1} & \cdots & \mathbf{m}''_{2j-1,2n-1} \\ \vdots & \vdots & \ddots & \vdots & \ddots & \vdots \\ \mathbf{m}''_{2n-1,1} & \mathbf{m}''_{2n-1,3} & \cdots & \mathbf{m}''_{2n-1,2i-1} & \cdots & \mathbf{m}''_{2n-1,2n-1} \end{bmatrix}, \bar{\bar{\bar{\mathbf{m}}}}_{j,i} = \begin{bmatrix} 0 & m_2 \\ m_2 & 0 \end{bmatrix}$

553 $\bar{\bar{\mathbf{k}}}_1 = \begin{bmatrix} \mathbf{m}'''_{1,1} & \mathbf{m}'''_{1,3} & \cdots & \mathbf{m}'''_{1,2i-1} & \cdots & \mathbf{m}'''_{1,2n-1} \\ \mathbf{m}'''_{3,1} & \mathbf{m}'''_{3,3} & \cdots & \mathbf{m}'''_{3,2i-1} & \cdots & \mathbf{m}'''_{3,2n-1} \\ \vdots & \vdots & \ddots & \vdots & \ddots & \vdots \\ \mathbf{m}'''_{2j-1,1} & \mathbf{m}'''_{2j-1,3} & \cdots & \mathbf{m}'''_{2j-1,2i-1} & \cdots & \mathbf{m}'''_{2j-1,2n-1} \\ \vdots & \vdots & \ddots & \vdots & \ddots & \vdots \\ \mathbf{m}'''_{2n-1,1} & \mathbf{m}'''_{2n-1,3} & \cdots & \mathbf{m}'''_{2n-1,2i-1} & \cdots & \mathbf{m}'''_{2n-1,2n-1} \end{bmatrix}, \bar{\bar{\mathbf{m}}}_{j,i} = \begin{bmatrix} 0 & 0 \\ 0 & m_4 \end{bmatrix},$

554 Also, as given by Eq. (16), the geometric stiffness matrix \mathbf{k}_{g1} can be expressed by

555 $\mathbf{k}_{g1} = \bar{\mathbf{k}}_{g1} + b_{cr} \bar{\bar{\mathbf{k}}}_{g1}$

556

557 $\bar{\mathbf{k}}_{g1} = \begin{bmatrix} \mathbf{n}'_{1,1} & \mathbf{n}'_{1,3} & \cdots & \mathbf{n}'_{1,2i-1} & \cdots & \mathbf{n}'_{1,2n-1} \\ \mathbf{n}'_{3,1} & \mathbf{n}'_{3,3} & \cdots & \mathbf{n}'_{3,2i-1} & \cdots & \mathbf{n}'_{3,2n-1} \\ \vdots & \vdots & \ddots & \vdots & \ddots & \vdots \\ \mathbf{n}'_{2j-1,1} & \mathbf{n}'_{2j-1,3} & \cdots & \mathbf{n}'_{2j-1,2i-1} & \cdots & \mathbf{n}'_{2j-1,2n-1} \\ \vdots & \vdots & \ddots & \vdots & \ddots & \vdots \\ \mathbf{n}'_{2n-1,1} & \mathbf{n}'_{2n-1,3} & \cdots & \mathbf{n}'_{2n-1,2i-1} & \cdots & \mathbf{n}'_{2n-1,2n-1} \end{bmatrix}, \bar{\bar{\mathbf{n}}}_{j,i} = \begin{bmatrix} 0 & m_5 \\ m_6 & 0 \end{bmatrix}$

$$\mathbf{k}_{g12} = \begin{bmatrix} \mathbf{n}''_{1,1} & \mathbf{n}''_{1,3} & \cdots & \mathbf{n}''_{1,2i-1} & \cdots & \mathbf{n}''_{1,2n-1} \\ \mathbf{n}''_{3,1} & \mathbf{n}''_{3,3} & \cdots & \mathbf{n}''_{3,2i-1} & \cdots & \mathbf{n}''_{3,2n-1} \\ \vdots & \vdots & \ddots & \vdots & \ddots & \vdots \\ \mathbf{n}''_{2j-1,1} & \mathbf{n}''_{2j-1,3} & \cdots & \mathbf{n}''_{2j-1,2i-1} & \cdots & \mathbf{n}''_{2j-1,2n-1} \\ \vdots & \vdots & \ddots & \vdots & \ddots & \vdots \\ \mathbf{n}''_{2n-1,1} & \mathbf{n}''_{2n-1,3} & \cdots & \mathbf{n}''_{2n-1,2i-1} & \cdots & \mathbf{n}''_{2n-1,2n-1} \end{bmatrix}, \bar{\mathbf{n}}_{j,i} = \begin{bmatrix} 0 & 0 \\ 0 & m_7 \end{bmatrix}$$

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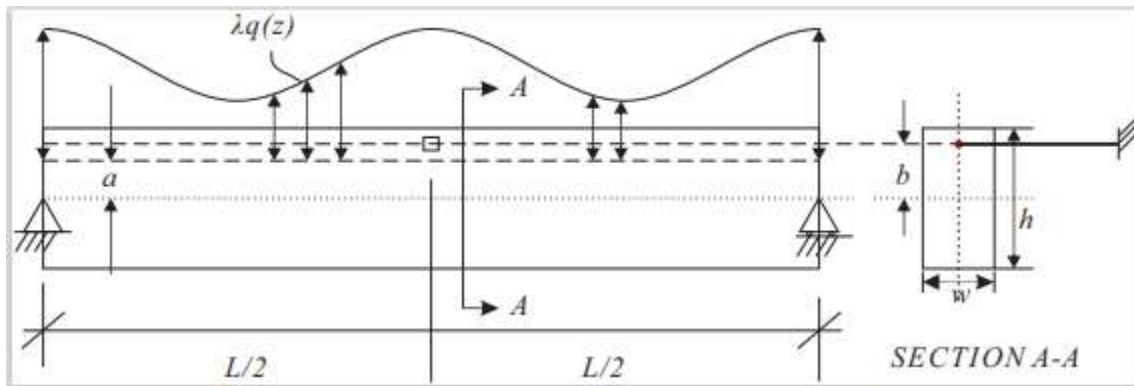
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Table 1 Assessing accuracy of bracing heights predictions

	a/h	bcr/h-based on simplified expression	bcr/h-based on ABAQUS	Difference
Point load	-0.25	-0.458	-0.495	3.72%
	0.00	-0.286	-0.289	0.26%
	0.25	-0.115	-0.123	0.80%
	0.50	0.057	0.107	4.96%
Uniformly distributed load	-0.25	-0.410	-0.433	2.25%
	0.00	-0.346	-0.330	1.62%
	0.25	-0.263	-0.242	2.08%
	0.50	-0.158	-0.138	2.00%

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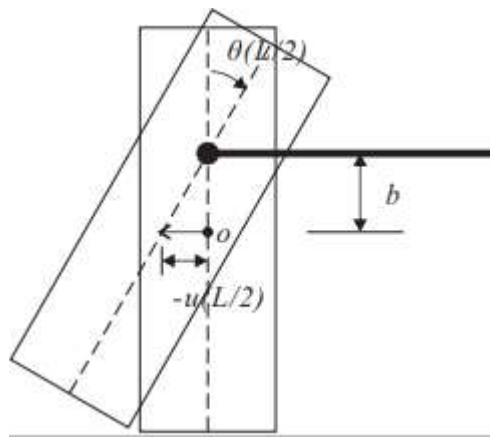
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Fig.1 Load height and brace effect



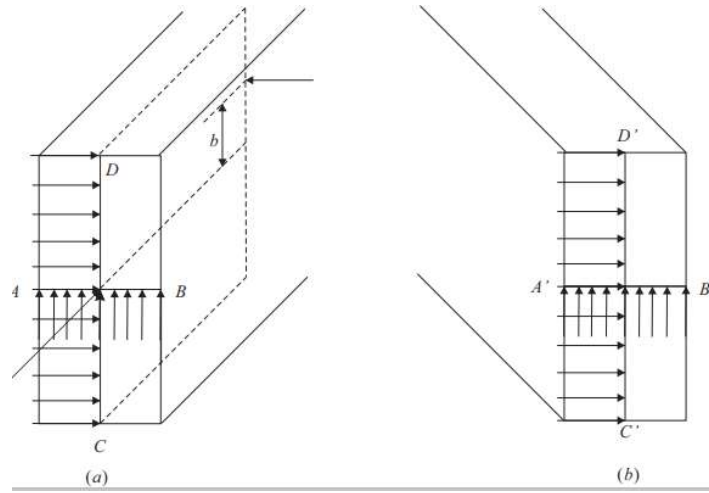
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Fig.2 Beam cross section at mid-span

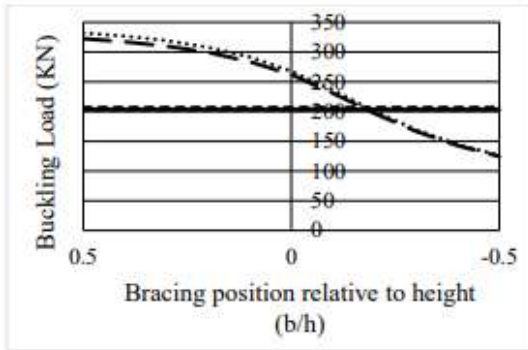
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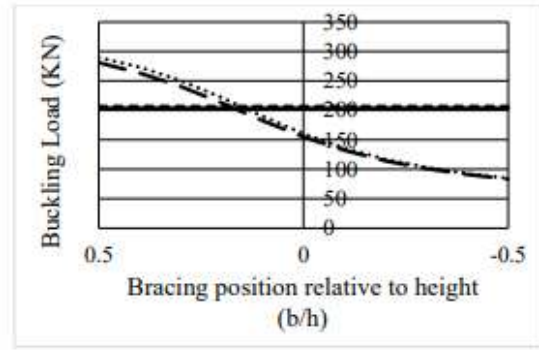
688

689 **Fig. 3** Boundary conditions (all arrows denote restrained degree of freedoms) (a) left end (b) right end

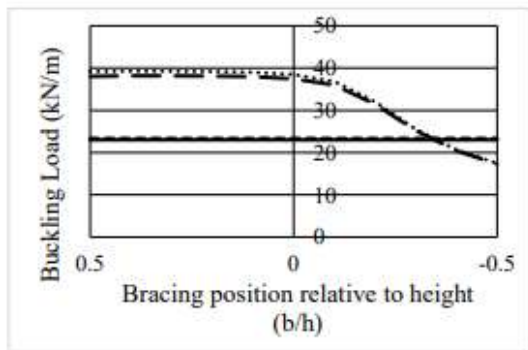
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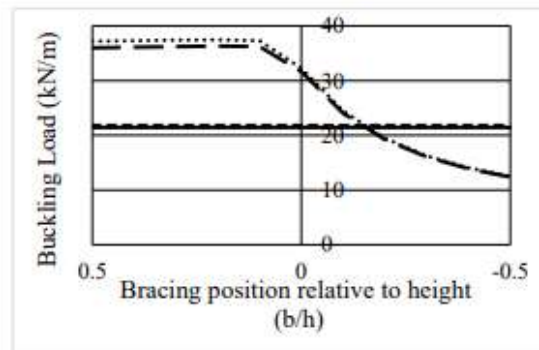
(a)



(b)



(c)



(d)

..... Present Study-Symmetric-n=9 -.-.- Present Study-Antisymmetric-n=9
 --- ABAQUS-Symmetric ——— ABAQUS-Antisymmetric

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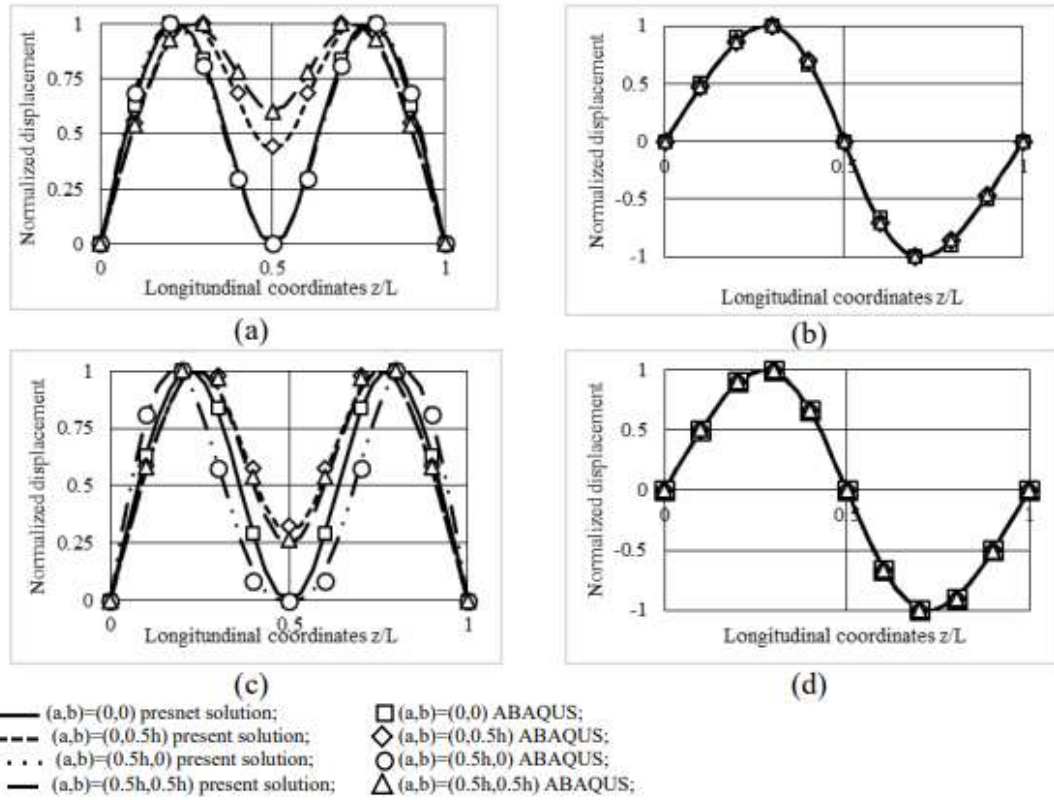
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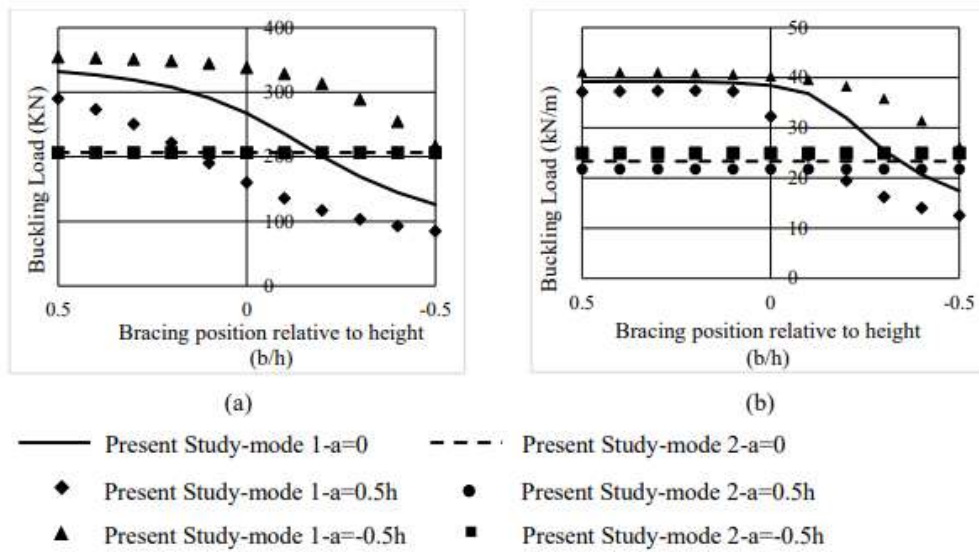
Fig. 4 Buckling load comparison relative to different bracing height when load is (a) point load, mid-height $a = 0$
 (b) point load, top face $a = 0.5h$ (c) uniformly distributed load, mid-height $a = 0$ (d) uniformly distributed load, top
 face $a = 0.5h$



696

697 **Fig.5** Comparison of buckling mode shapes between present study and ABAQUS (a) point load-symmetric mode,
 698 (b) point load-anti-symmetric mode, (c) uniformly distributed load-symmetric mode, and (d) uniformly distributed
 699 load-anti-symmetric mode

700



701

702 **Fig. 6** Effect of brace position under for different load heights (a) point load (b) uniformly distributed load