

# Geodesics in the Heisenberg group

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## Objective:

The goal is to obtain the geodesic equations in the Heisenberg group. These will allow to map surfaces such that each point on the surface is the end of a geodesic of constant length.

## Heisenberg group and its operation:

$$H = \left\{ \begin{bmatrix} 1 & x & z \\ 0 & 1 & y \\ 0 & 0 & 1 \end{bmatrix} \mid x, y, z \in \mathbb{R} \right\} \text{ which is the Heisenberg group}$$

Now, we will define the following function  $\phi$  as follows:

$$\phi : \mathbb{R}^3 \rightarrow H$$

$$(x_1, x_2, x_3) \mapsto \begin{pmatrix} 1 & x_1 & x_3 + \frac{1}{2}x_1x_2 \\ 0 & 1 & x_2 \\ 0 & 0 & 1 \end{pmatrix}$$

One can show that

$$\begin{aligned} \phi(x, y, z)\phi(a, b, c) \\ = \phi(x + a, y + b, z + c + (xb - ya)/2) \end{aligned}$$

We will multiply two vectors in  $\mathbb{R}^3$  as follows:

$$(x, y, z) \odot (a, b, c) = (x + a, y + b, z + c + (xb - ya)/2)$$

The function  $\phi$  was obtained by taking the

$$\text{exponential map of the matrix } \begin{bmatrix} 0 & x_1 & x_3 \\ 0 & 0 & x_2 \\ 0 & 0 & 0 \end{bmatrix}$$

In order to obtain geodesics, we need to define a metric on the Heisenberg group. We will first define two maps which will allow us to do so.

Let us define the following functions:

$$\begin{aligned} \mu_x: H &\rightarrow H \\ y &\mapsto x \odot y \end{aligned}$$

Now, let  $\gamma$  be a curve in  $H$  with  $\gamma(0) = y$  and  $\dot{\gamma}(0) = v \in T_y H$ . We define the function  $(\mu_x)_*$  as follows:

$$\begin{aligned} (\mu_x)_*: T_y H &\rightarrow T_{x \odot y} H \\ (\mu_x)_*(\gamma) &= \frac{d}{dt}(x \odot \gamma(t)) \end{aligned}$$

The metric defined in  $H$  will allow us to measure lengths. Using the previous maps we define our metric as follows:

Let  $v, w \in T_y H$ , then

$$g_y(v, w) = \left\langle (\mu_{y^{-1}})_*(v) \mid (\mu_{y^{-1}})_*(w) \right\rangle$$

Recall that in  $\mathbb{R}^n$  the length of a curve  $\gamma$  is given by  $l(\gamma) = \int_a^b \|\dot{\gamma}(t)\| dt$ . On an arbitrary manifold  $M$  with a metric:

$$l(\gamma) = \int_a^b g_{\gamma(t)}(\dot{\gamma}(t), \dot{\gamma}(t))^{1/2} dt$$

## Geodesics:

Geodesics are defined to be locally the shortest path between two points. Hence, in order to obtain geodesics in  $H$ , we must minimize the formula for the length of a curve. Using techniques of the calculation of variations, we obtain the geodesic equation given by:

$$\ddot{\gamma}_i(t) + \Gamma_{jk}^i \dot{\gamma}^j(t) \dot{\gamma}^k(t) = 0$$

$$\text{Where } \Gamma_{jk}^i = \frac{1}{2} g^{il} (\partial_j g_{kl} - \partial_l g_{jk} + \partial_k g_{lj})$$

$$\text{With } g_y(\partial_i, \partial_j) = g_{ij}(y)$$

$$\text{and } g^{ij}(y) g_{jk}(y) = \delta_k^i$$

The geodesic equation can be solved in  $H$  using the metric that we defined previously. We must also construct left invariant vector fields as follows:

$$\begin{aligned} X_1 &= \frac{d}{dt}((x, y, z) \odot (t, 0, 0))_{t=0} \\ &= \frac{d}{dt} \left( x + t, y, z - \frac{yt}{2} \right)_{t=0} \\ &= \left( 1, 0, -\frac{y}{2} \right) \\ &= \partial_1 - \frac{y}{2} \partial_3 \end{aligned}$$

$$\begin{aligned} X_2 &= \frac{d}{dt}((x, y, z) \odot (0, t, 0))_{t=0} \\ &= \frac{d}{dt} \left( x, y + t, z + \frac{xt}{2} \right)_{t=0} \\ &= \left( 0, 1, \frac{x}{2} \right) \\ &= \partial_2 + \frac{x}{2} \partial_3 \end{aligned}$$

$$\begin{aligned} X_3 &= \frac{d}{dt}((x, y, z) \odot (0, 0, t))_{t=0} \\ &= \frac{d}{dt} (x, y, z + t)_{t=0} \\ &= (0, 0, 1) \\ &= \partial_3 \end{aligned}$$

After differentiating  $\gamma$  with respect to  $t$ , we get:  $\gamma' = x' \partial_1 + y' \partial_2 + z' \partial_3$ , so that we have:

$$\gamma' = x' X_1 + y' X_2 + \left( \frac{x'y}{2} - \frac{y'x}{2} + z' \right) X_3$$

With  $\nabla_{\frac{\partial}{\partial x^i}} \left( \frac{\partial}{\partial x^i} \right) = \Gamma_{jk}^i \frac{\partial}{\partial x^k}$  we have that

$\nabla_{\gamma'}(\gamma') = 0$  which is equivalent to the geodesic equation.

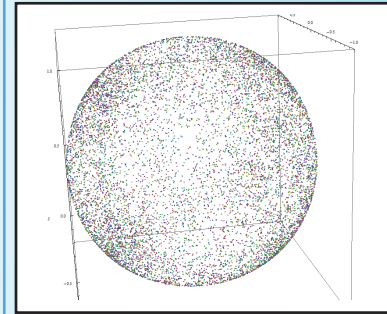
## Geodesic surfaces:

Solving the geodesic equation, we obtain the following set of differential equations:

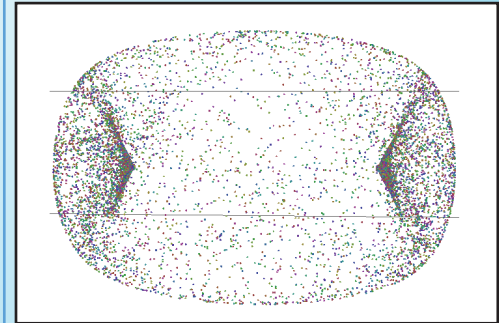
$$\begin{aligned} x'' + y' z'_0 &= 0 \\ x'' + (y'_0 + x z'_0) z'_0 &= 0 \\ x'' + y'_0 z'_0 + x z'_0{}^2 &= 0 \\ x'' + x z'_0{}^2 + y'_0 z'_0 &= 0 \end{aligned}$$

The following illustrations are surfaces traced by the ends of geodesics of equal length. We let  $L$  denote the length of the geodesic curves.

$L = 1$



$L = 7$



$L = 25$

